

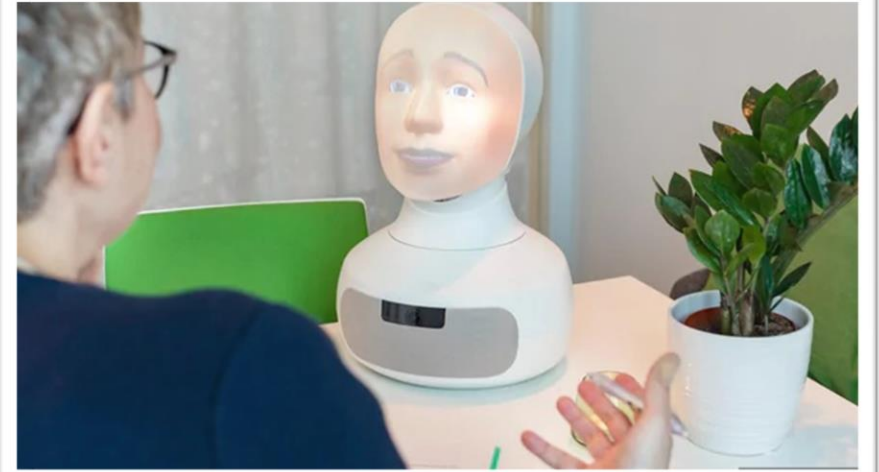


Predictive Modelling of Turn-Taking in Human-Robot Interaction

Gabriel Skantze

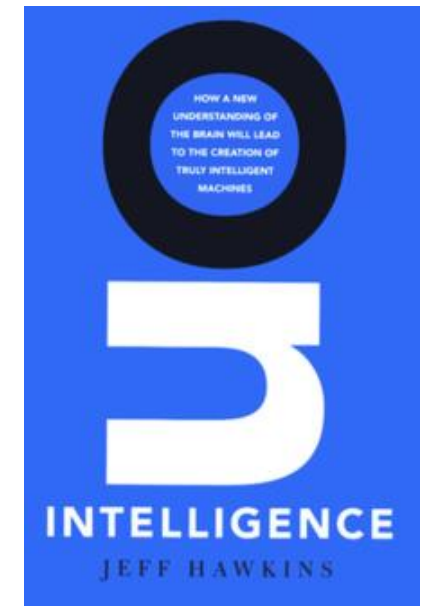
Professor in Speech Technology, KTH

Co-founder and Chief Scientist, Furhat Robotics



Predictive modelling

- Predictive modelling = a statistical or machine learning technique used to predict future outcomes based on historical data
- Predictive modelling on spoken interaction = predict future speech activity based on historical data (the spoken interaction so far)
- Why do we want to do this?
 - Predictive modelling is useful (crucial?) for an agent/robot taking part in an interaction
 - Predictive modelling useful for an agent to learn representations of the data
 - Intelligence = Ability to predict the future? (Hawkins)
 - Bayesian Brain hypothesis



Large Language Models (ChatGPT)

There

There once

There once was

There once was a

There once was a prince

There once was a prince who

There once was a prince who lived

There once was a prince who lived in

There once was a prince who lived in a

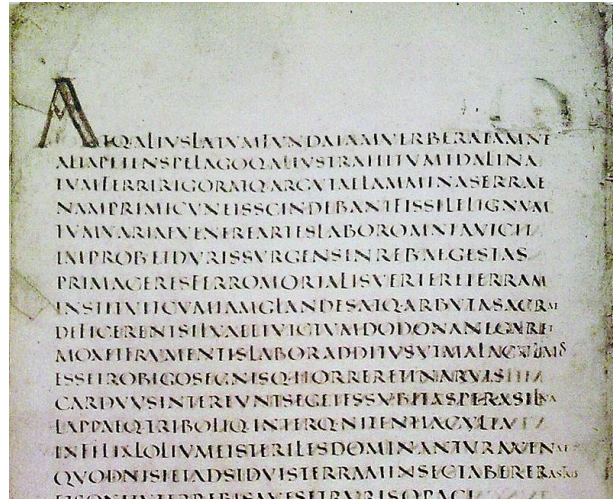
There once was a prince who lived in a castle



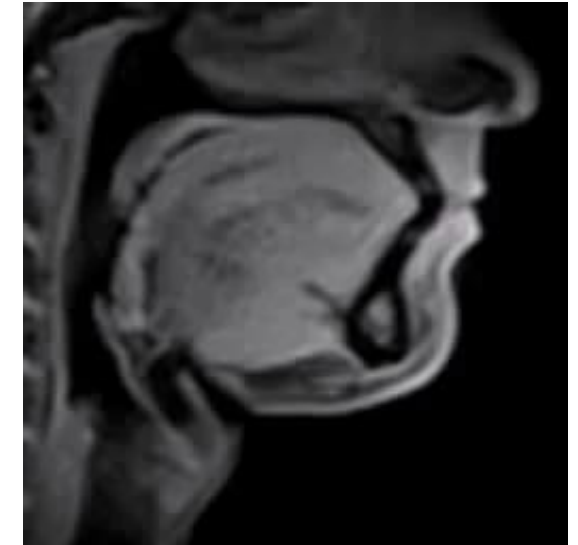
attention



Cuneiform, 3500BC



Vergilius Augusteus, 4th Century



Written Language	Spoken Language
Used since 5000 years	Used since at least 100.000 years
Words, letters, spaces, punctuation	Continuous, Highly variable, ambiguous and noisy
Asynchronous communication	Real-time communication
Syntactically well-formed	Disfluent (Repetitions, hesitations, truncated words, etc)
Exclusively symbolic & verbal (<i>what</i> we say)	Non-symbolic & non-verbal components (<i>how</i> we talk: prosody, laughter, breathing, etc)

Spoken conversation is a Joint Activity happening in real time

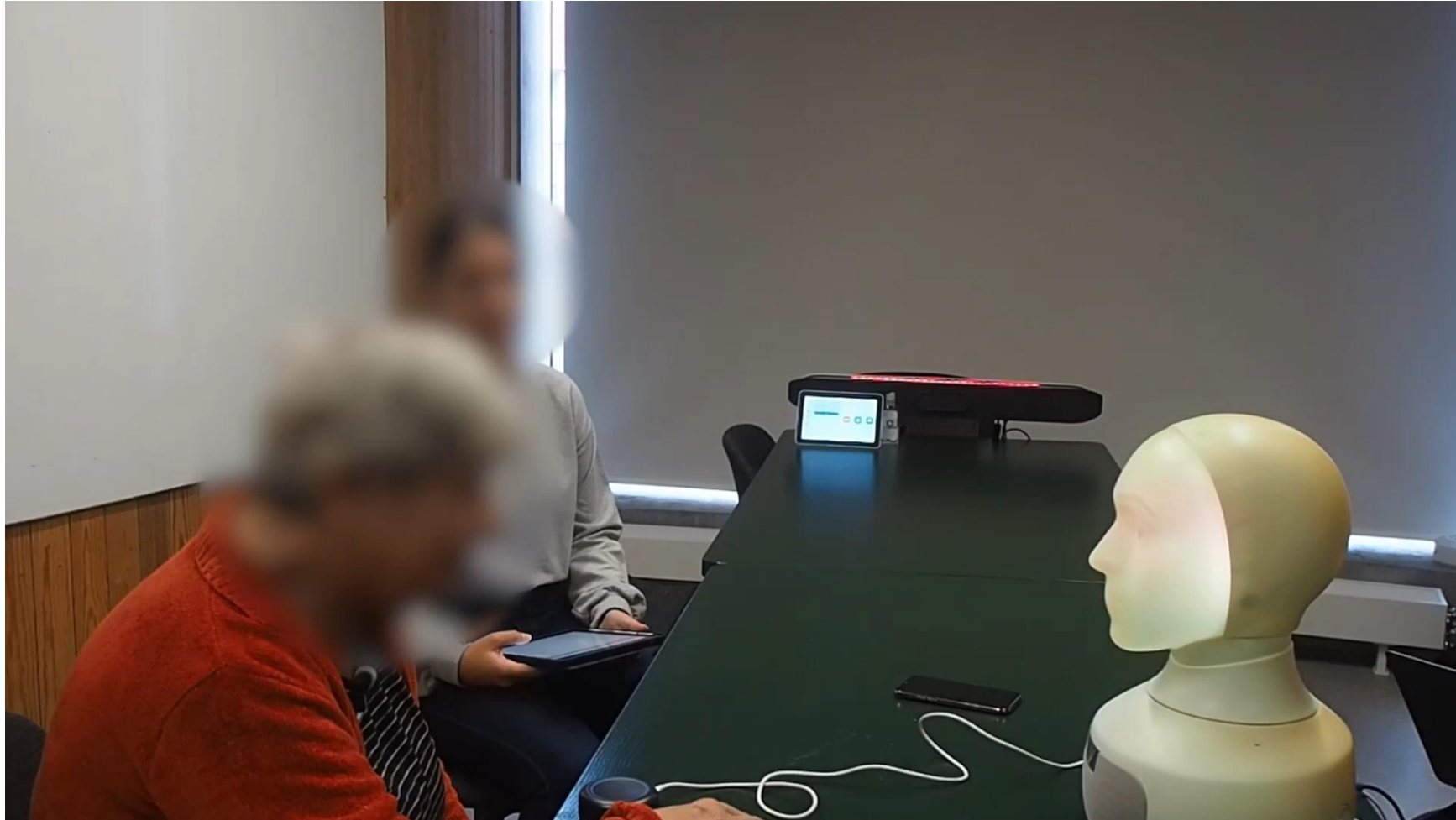


Coordination relies on cues and signals (in the face and the voice)

Coordination requires the ability to anticipate (predict) the partner's actions

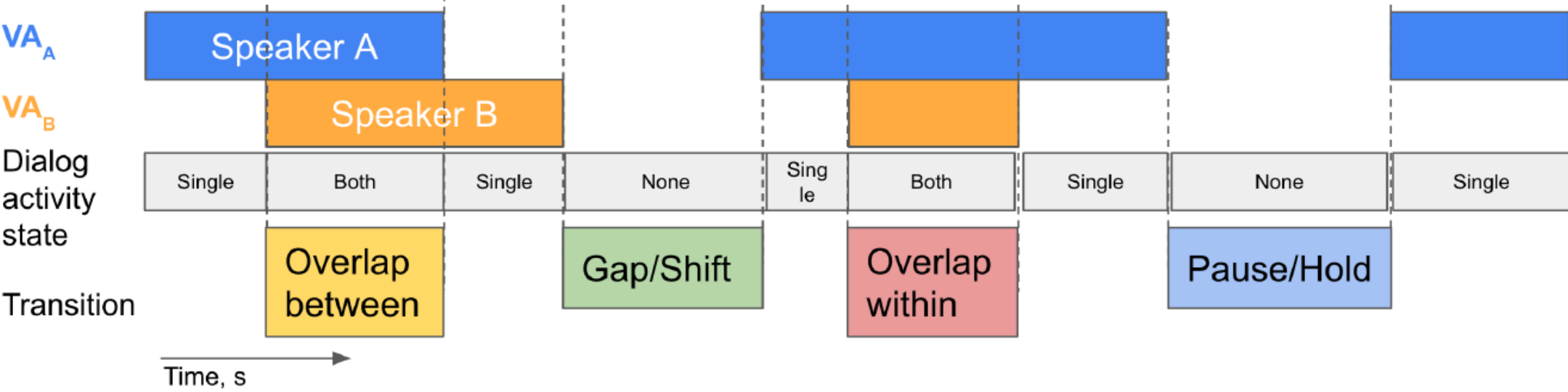
Purely reactive approaches are not enough!

Failed turn-taking

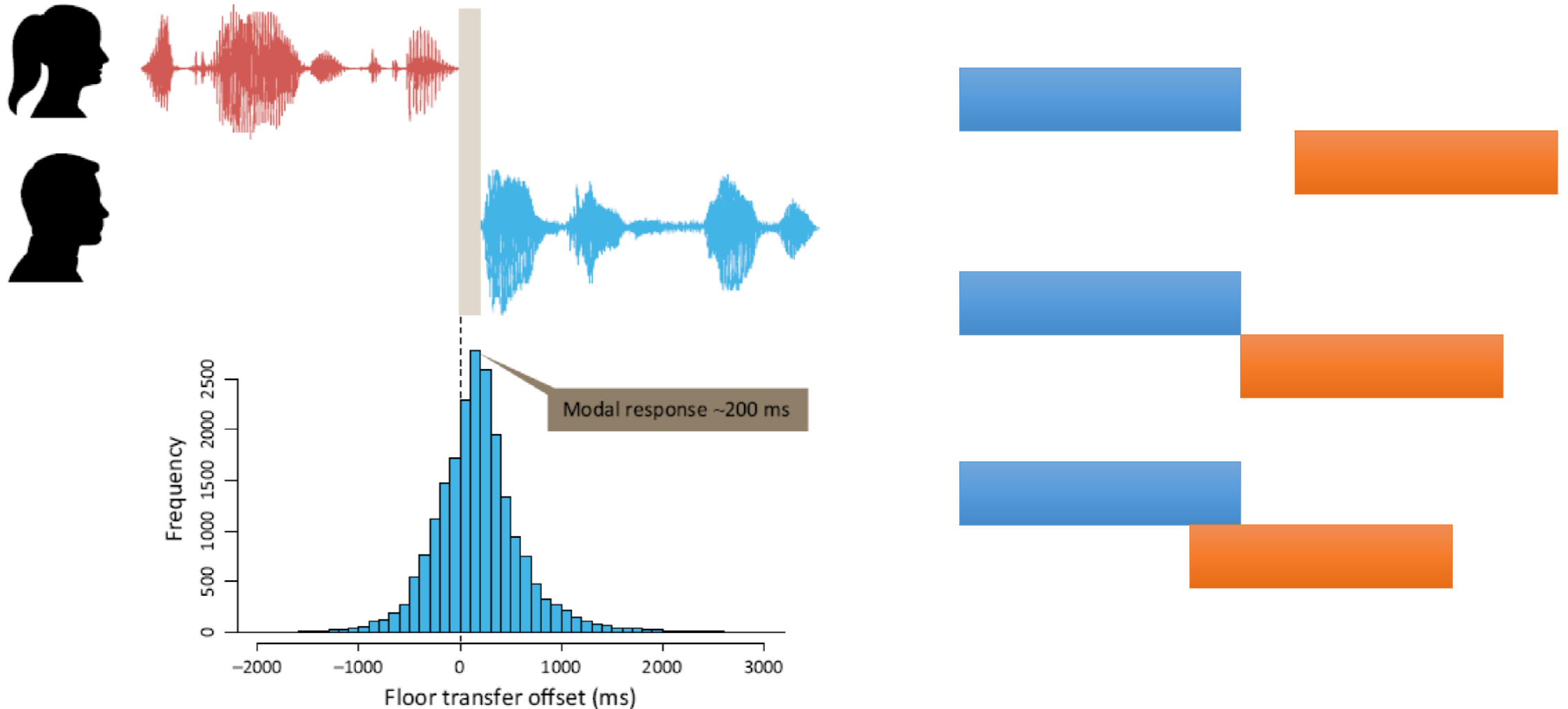


Irfan, B., Kuoppamäki, S.-M., & Skantze, G. (2023). *Between Reality and Delusion: Challenges of Applying Large Language Models to Companion Robots for Open-Domain Dialogues with Older Adults*. <https://doi.org/10.21203/rs.3.rs-2884789/v1>

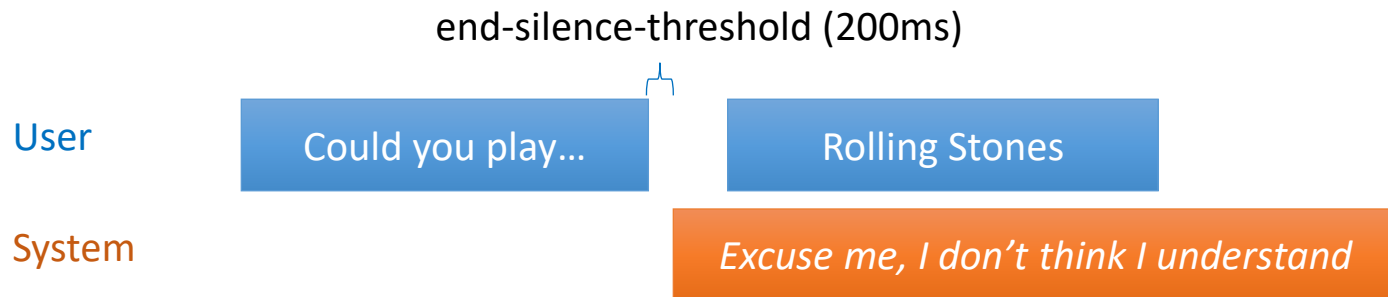
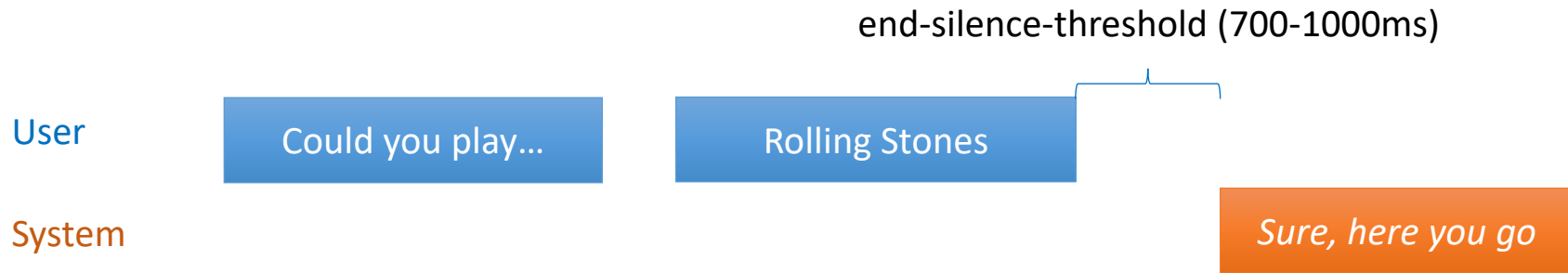
Terminology



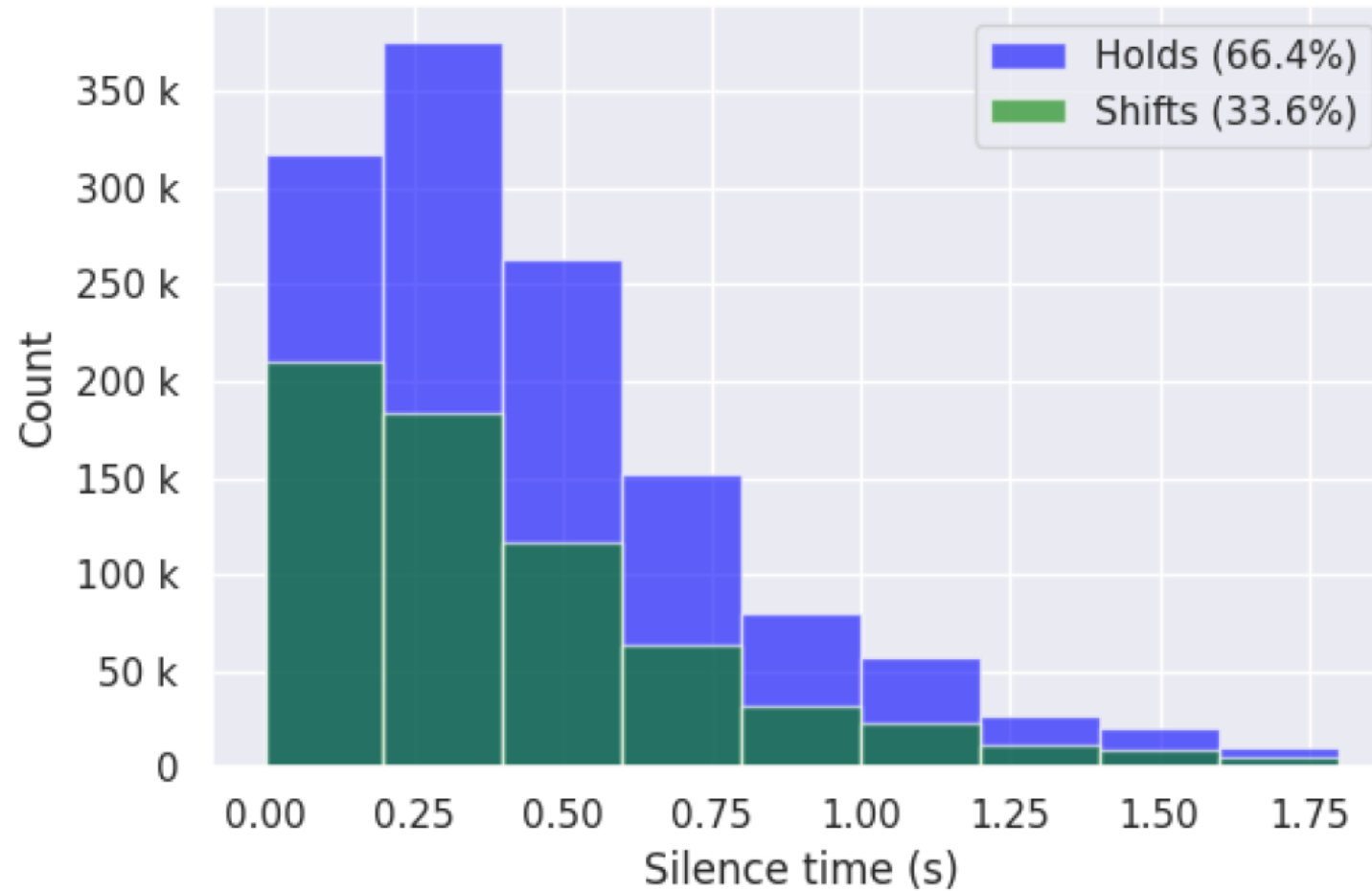
Coordination of turn-taking in spoken interaction



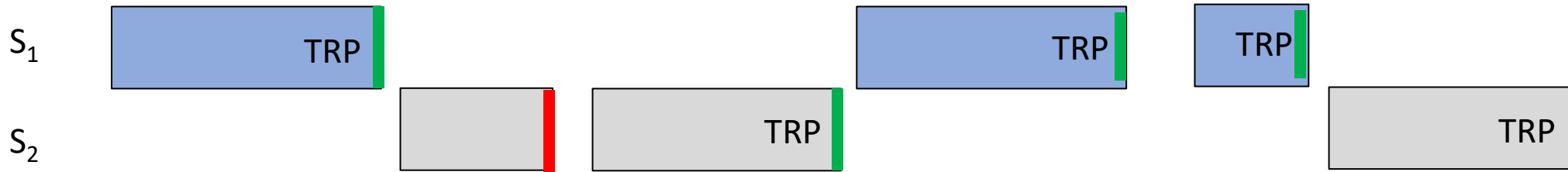
Turn-taking in current systems



Silence is a bad indicator of turn-taking



Coordination signals across modalities

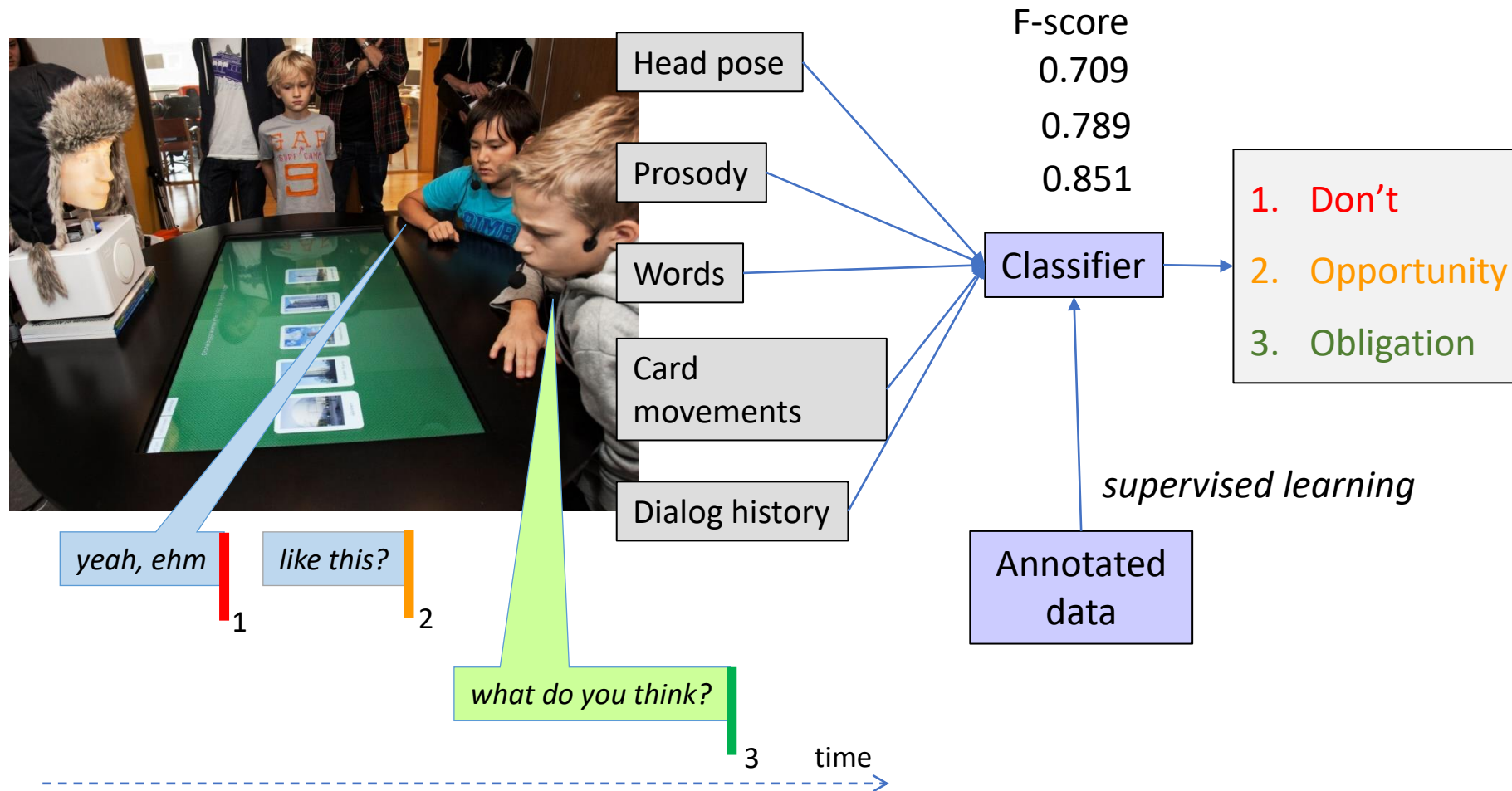


	Turn-yielding cue	Turn-holding cue
Verbal/Syntax	Complete	Incomplete, Fillers
Prosody - Pitch	Rising or Falling	Flat
Prosody - Intensity	Lower	Higher
Prosody - Duration	Shorter	Longer
Breathing	Breathe out	Breathe in
Gaze	Looking at addressee	Looking away
Gesture	Terminated	Non-terminated

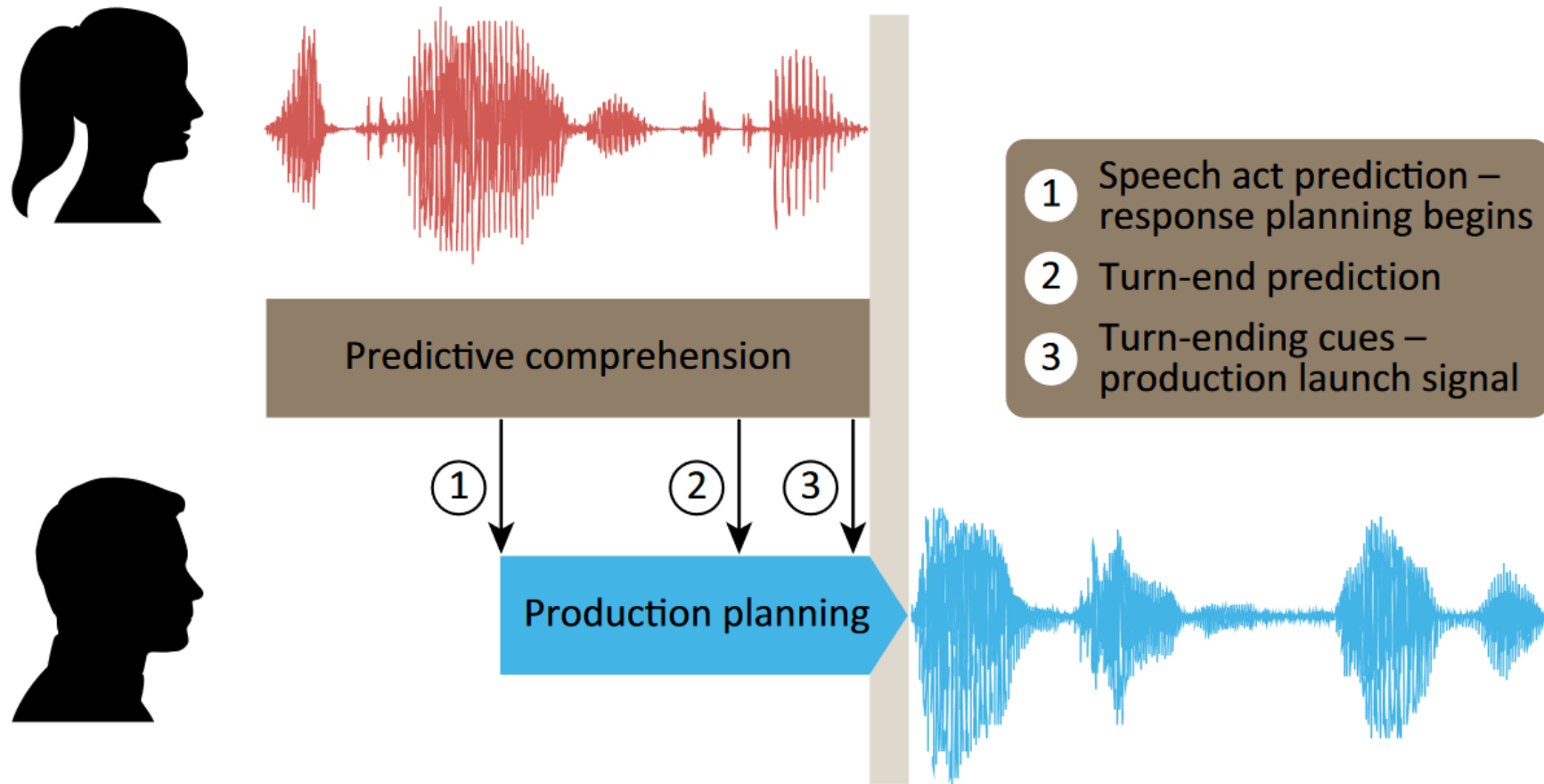
TRP = Transition Relevance-Place
(Sacks et al, 1974)

The more cues, the stronger the signal! (*Duncan, 1972*)

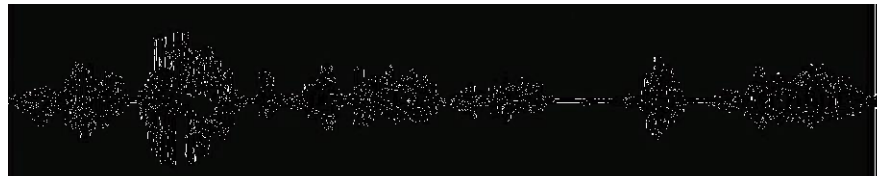
As simple classifier for identifying turn-taking cues



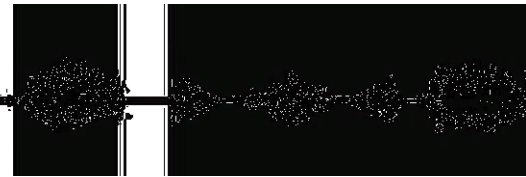
From reaction to prediction



Evidence of prediction



the have got extinct volcano
start-----you an



right okay you go



ehm down the s
left-hand



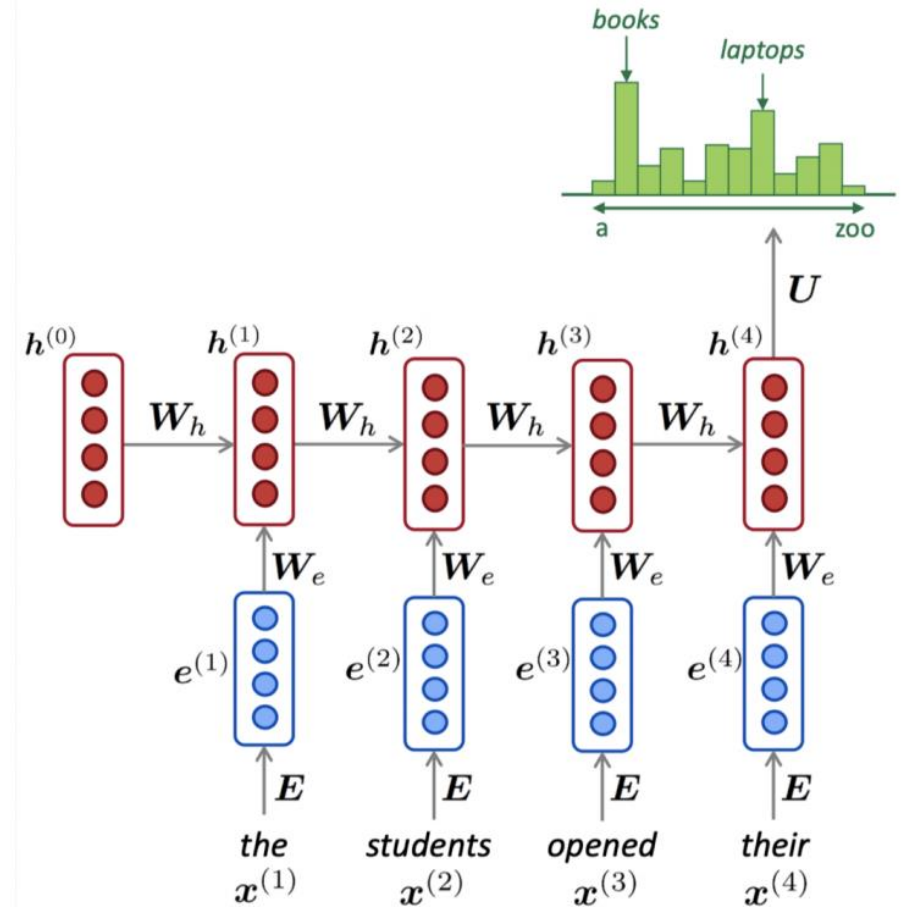
yeah just the of
it's at top it



okay

How can we predict the future in speech?

- Written language is made up of a sequence of discrete tokens from a fixed vocabulary
- Prediction of the next token can be formulated as a probability distribution over this vocabulary



TurnGPT: Modelling turn-taking with an LLM

- Turn completion is judged incrementally as the utterance unfolds:

What would you like <TC> to order? <TC>

I would like a hamburger <TC> with fries <TC> and a milkshake <TC>

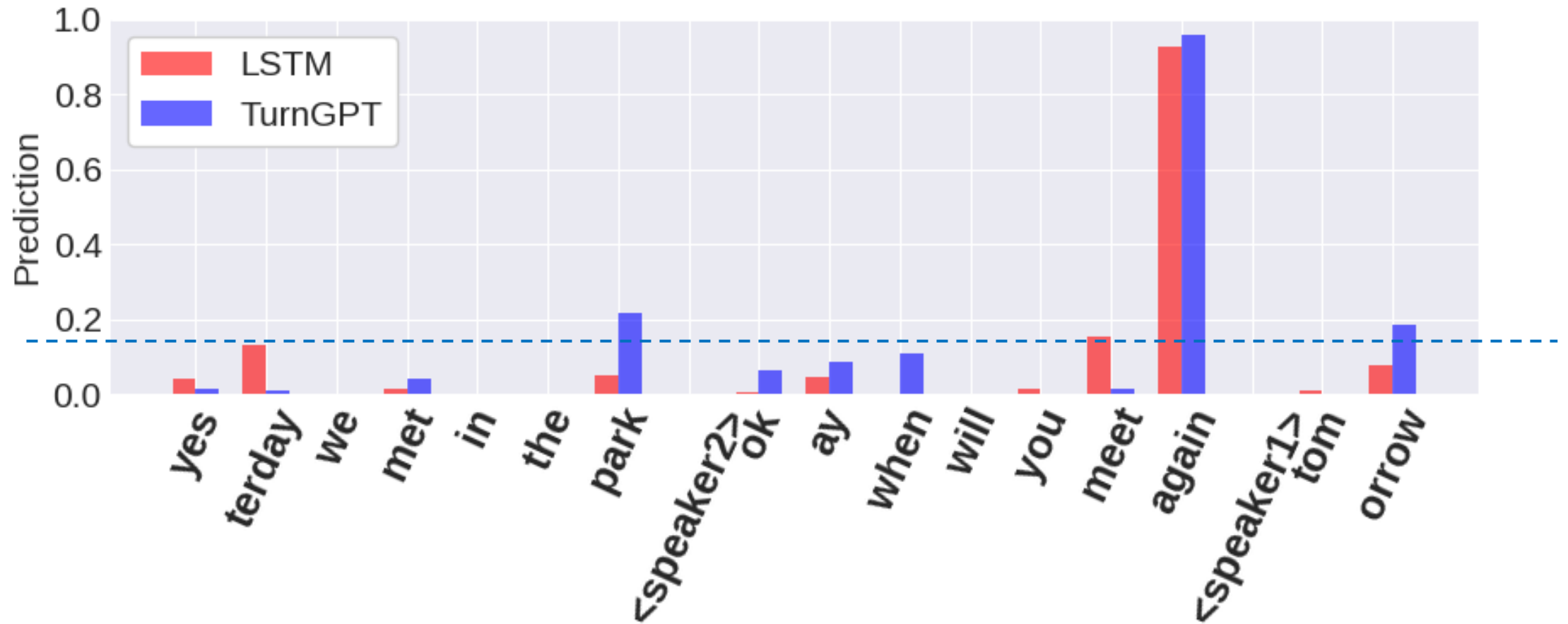
- Context dependence:

yesterday we met <TC> in the park <TC>

okay <TC> when <TC> will you meet again <TC>

tomorrow <TC>

TurnGPT: Probability of turn shifts



How can we predict the future in speech?

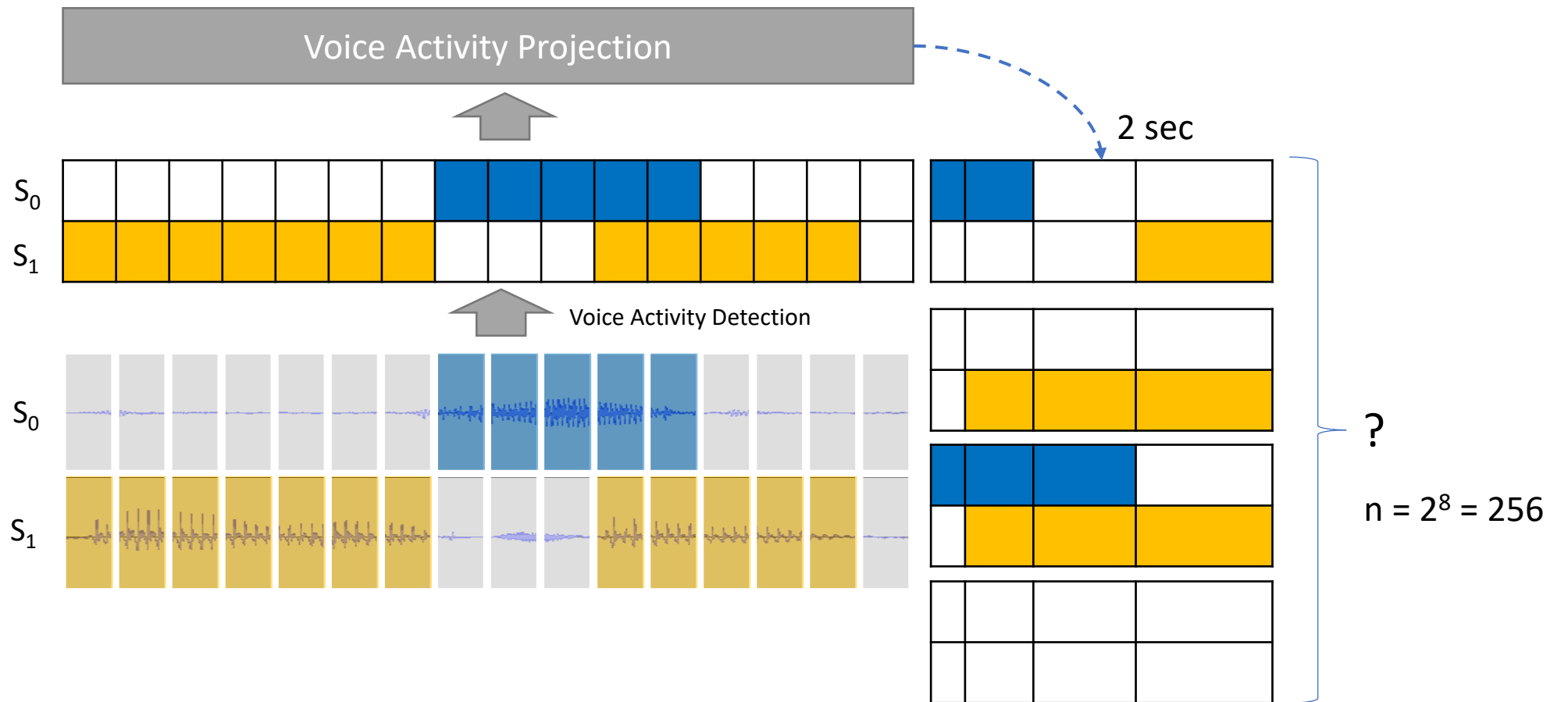
Speech is made up of a continuous sound wave.

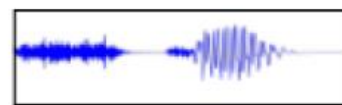
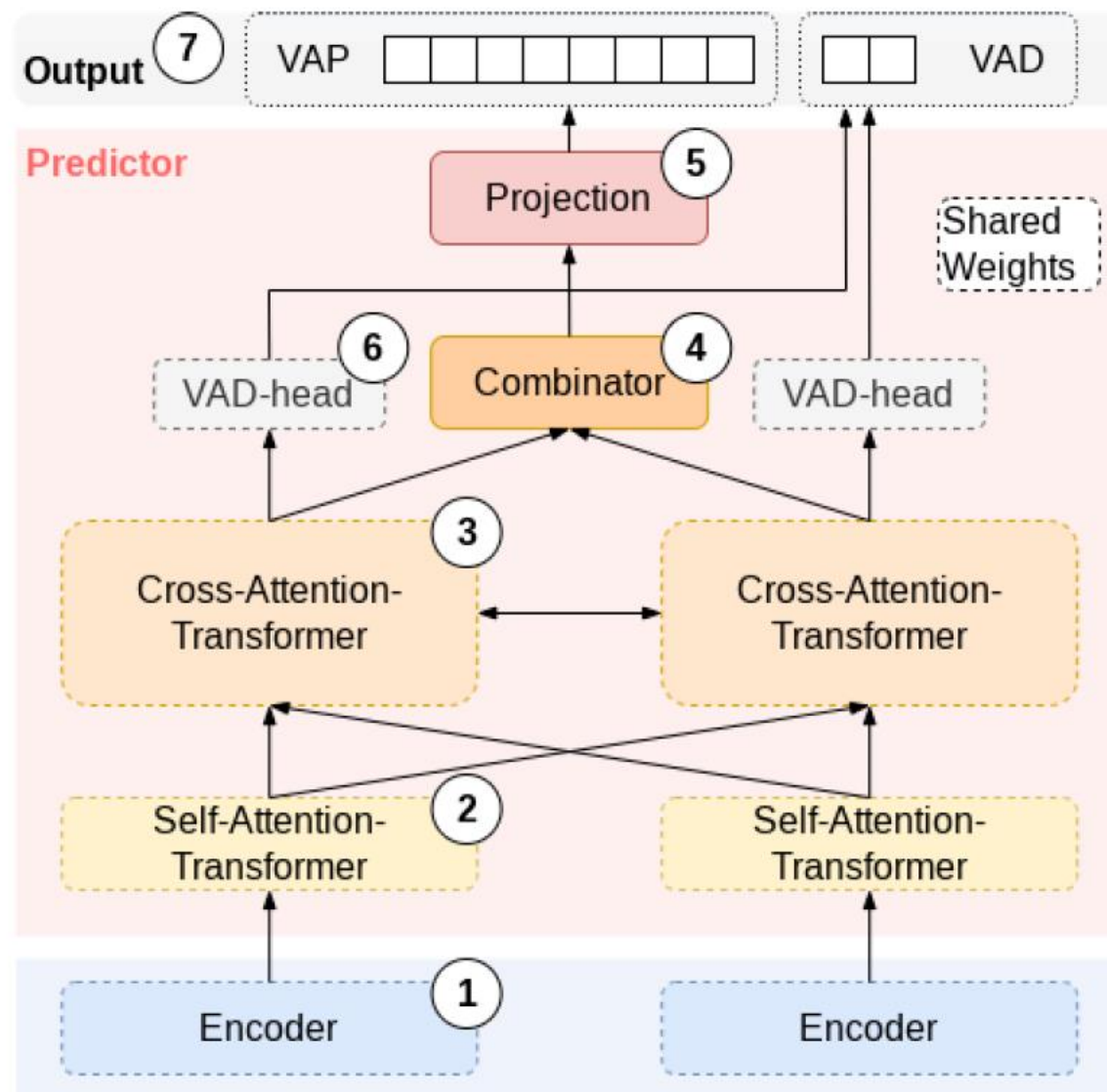
What is a “turn”, really?



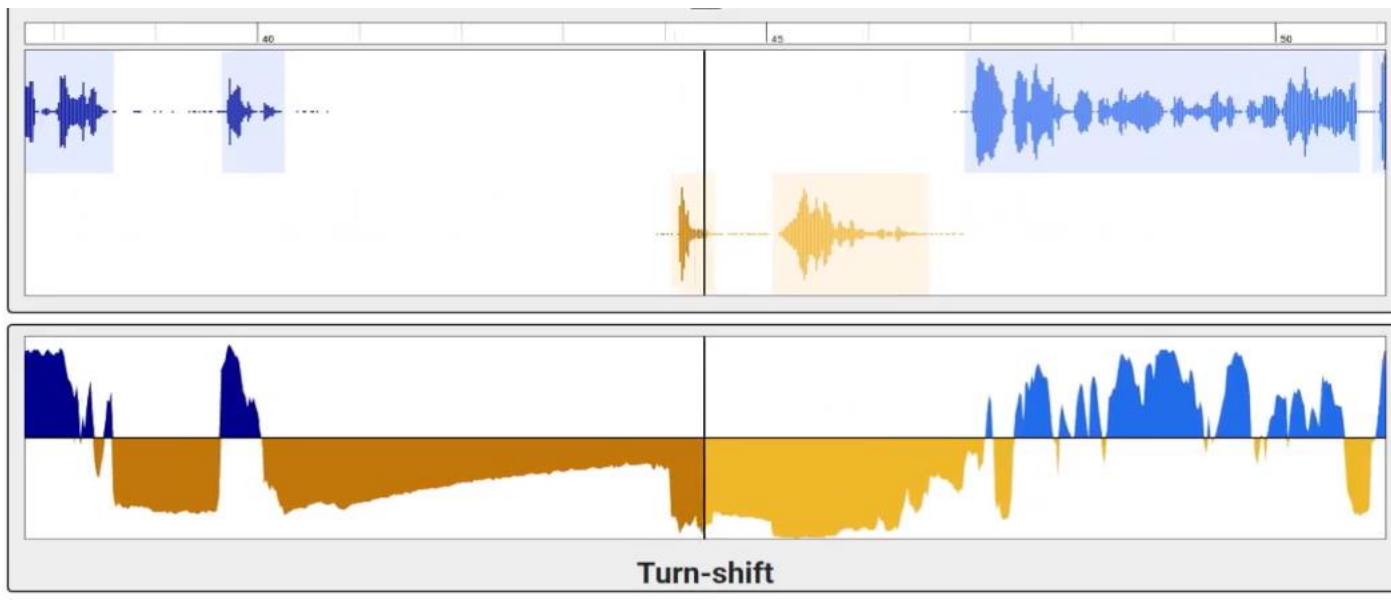
Not just words, but also prosody, timing, etc.

Voice Activity Projection (VAP)





VAP: A turn-taking model predicting the next 2 sec of a conversation

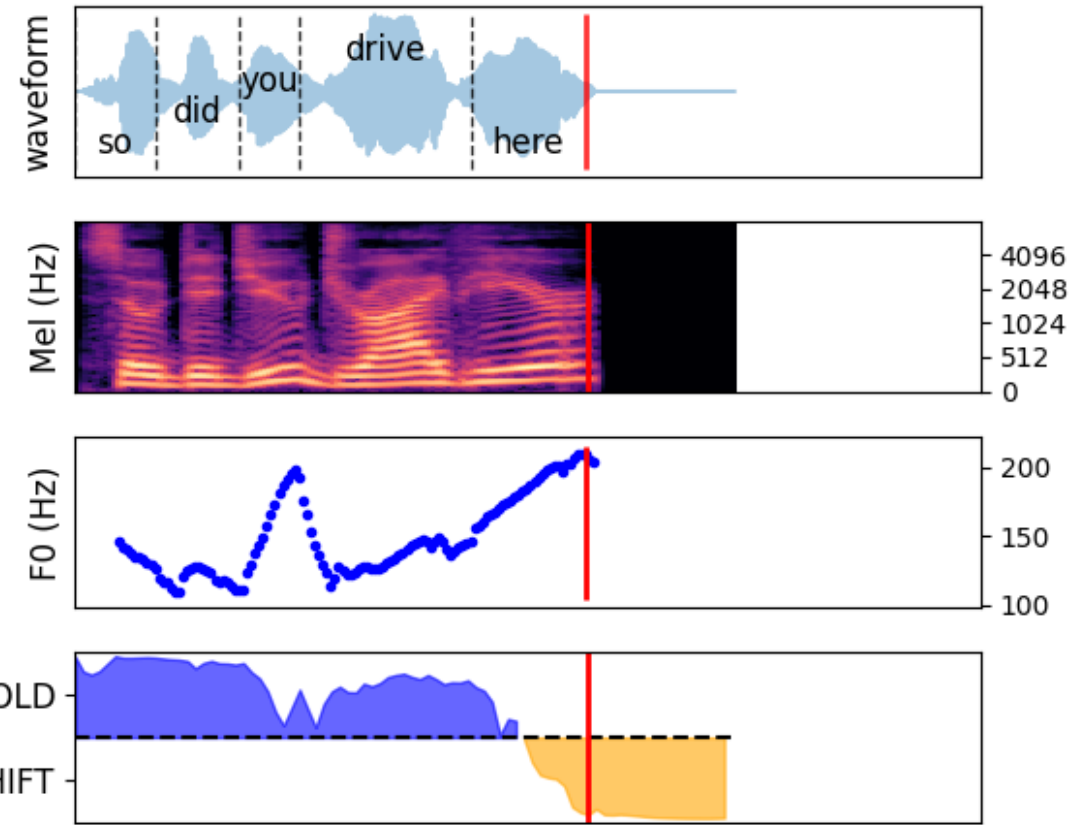
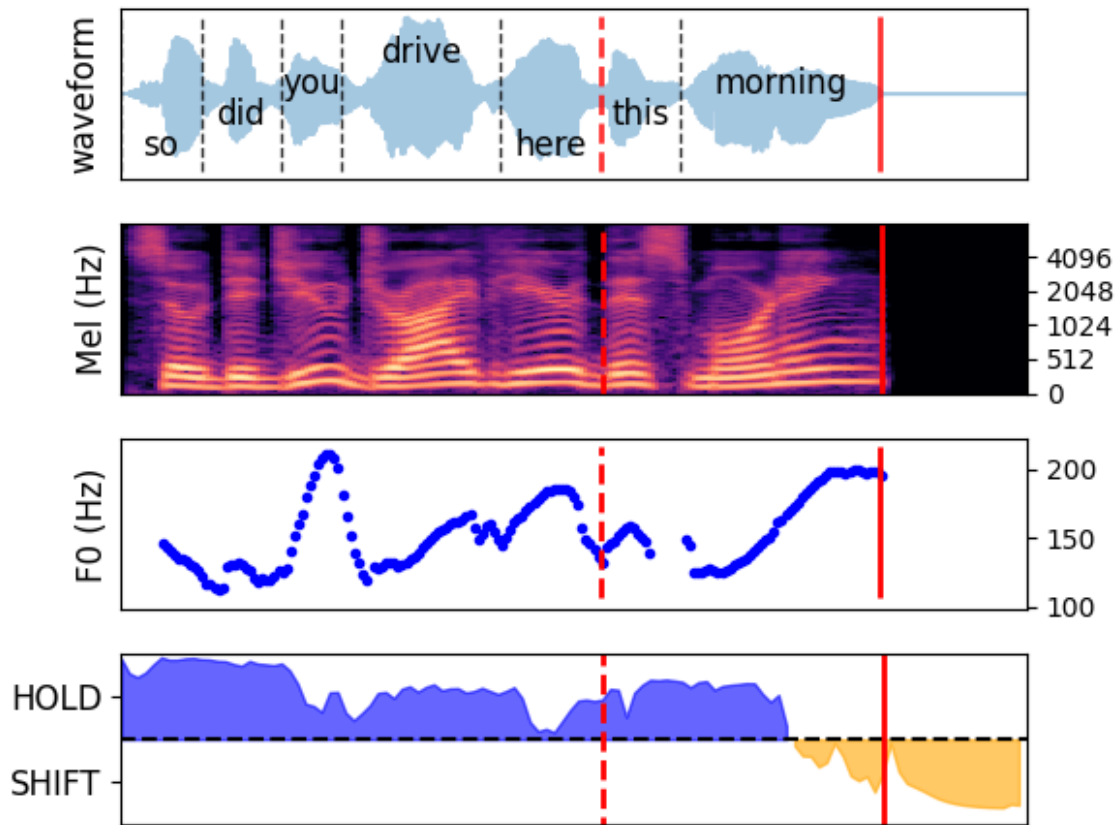


Advantages of Voice Activity Projection

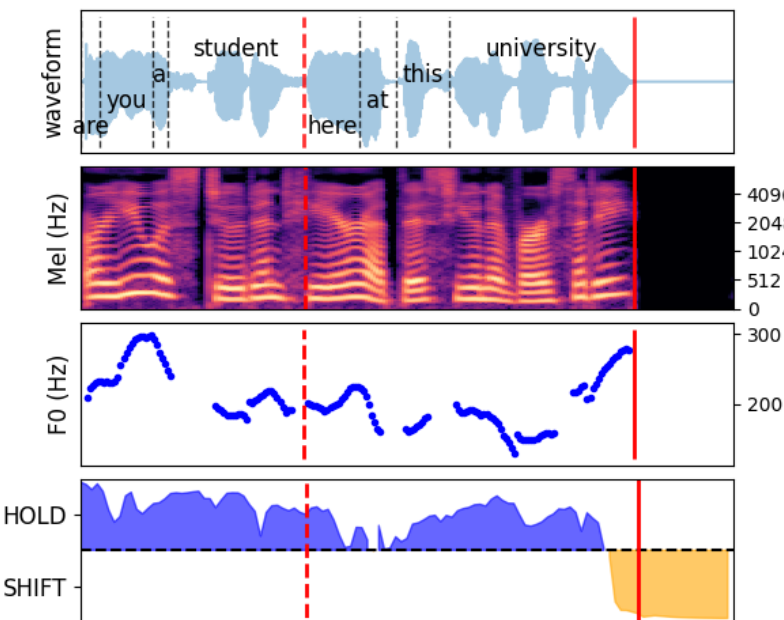
- Operates on raw audio
 - Pre-trained Contrastive Predictive Coding (CPC)
- No need for speech recognition (words) or feature extraction (prosody)
 - No need to normalize features to the speaker
 - Continuous modelling, no delay
- Only lightly annotated data needed (binary voice activity detection)
 - Can be trained on large amounts of (diverse) data
- BUT: Black-box model (trained end-to-end).
- What has it actually learned?

So, did you drive here **this morning**?

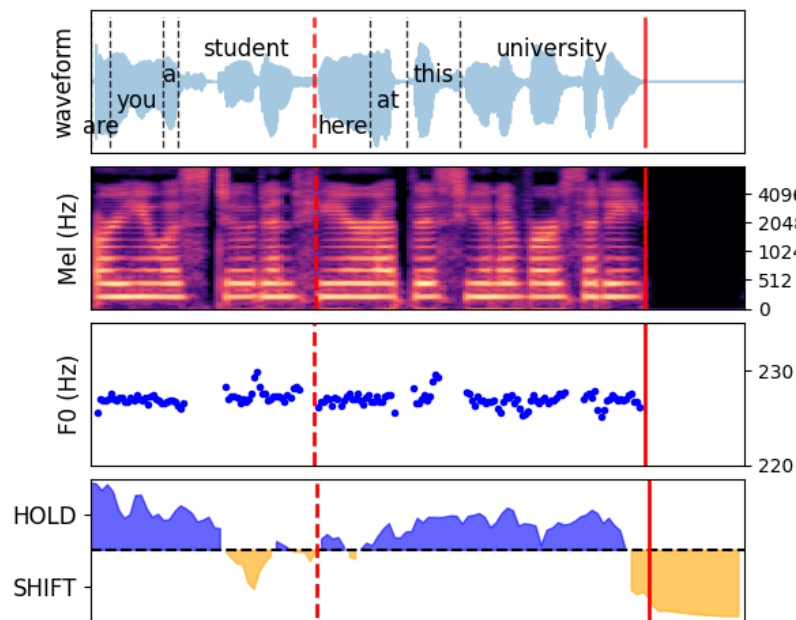
So, did you drive here?



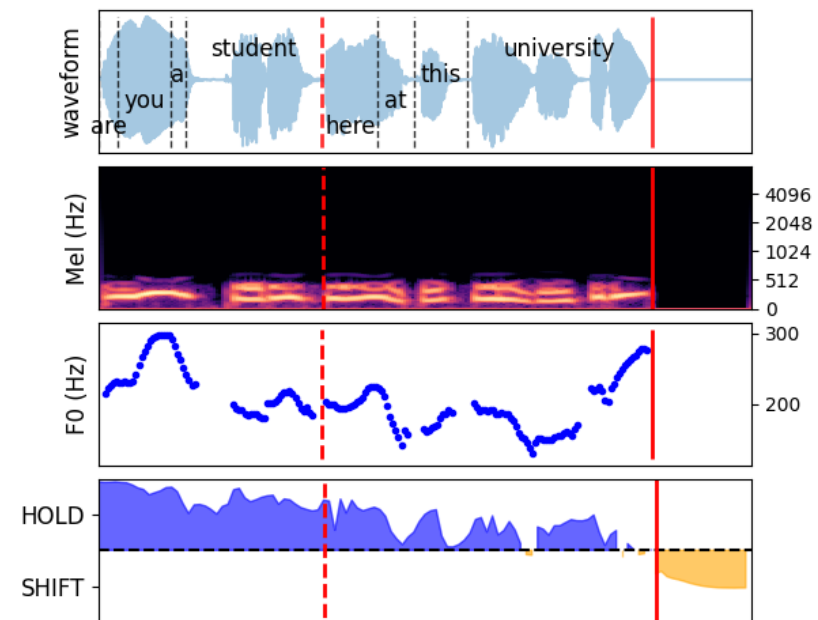
Original



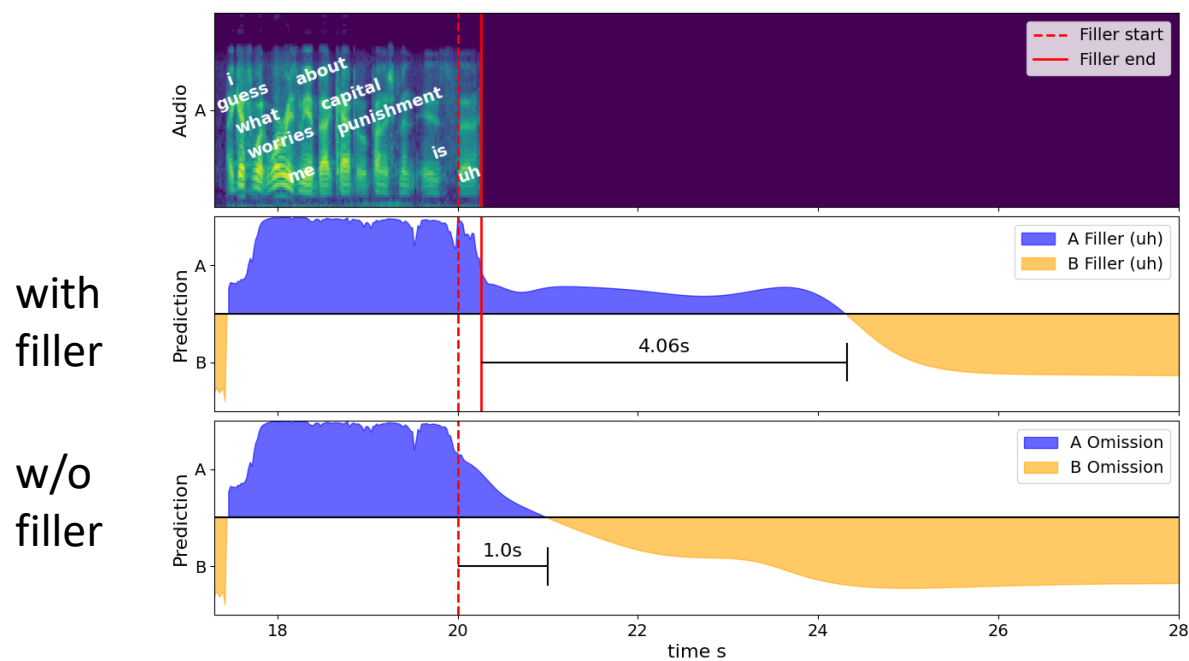
Flat pitch



Low pass



How much time does a filler “buy you”?



	coef	coef(exp)	SE	Pr(> z)
F0	-0.725	0.484	0.246	0.003
Intensity	-0.127	0.879	0.035	0.0003
Lex _{um}	-0.077	0.925	0.050	0.12
Duration	-0.118	0.888	0.037	0.001
Pos _{mid}	-0.305	0.736	0.065	<0.0001
F0:Lex _{um}	-1.237	0.237	0.290	0.007

Table 1: Model summary of the Cox regression model. Bold p values are significant.

Synthesizing turn-taking cues



User

Do you have any ABBA compilation?

System

Yes, I have ABBA gold

Do you want me to play it for you?

User

Do you have any ABBA compilation?

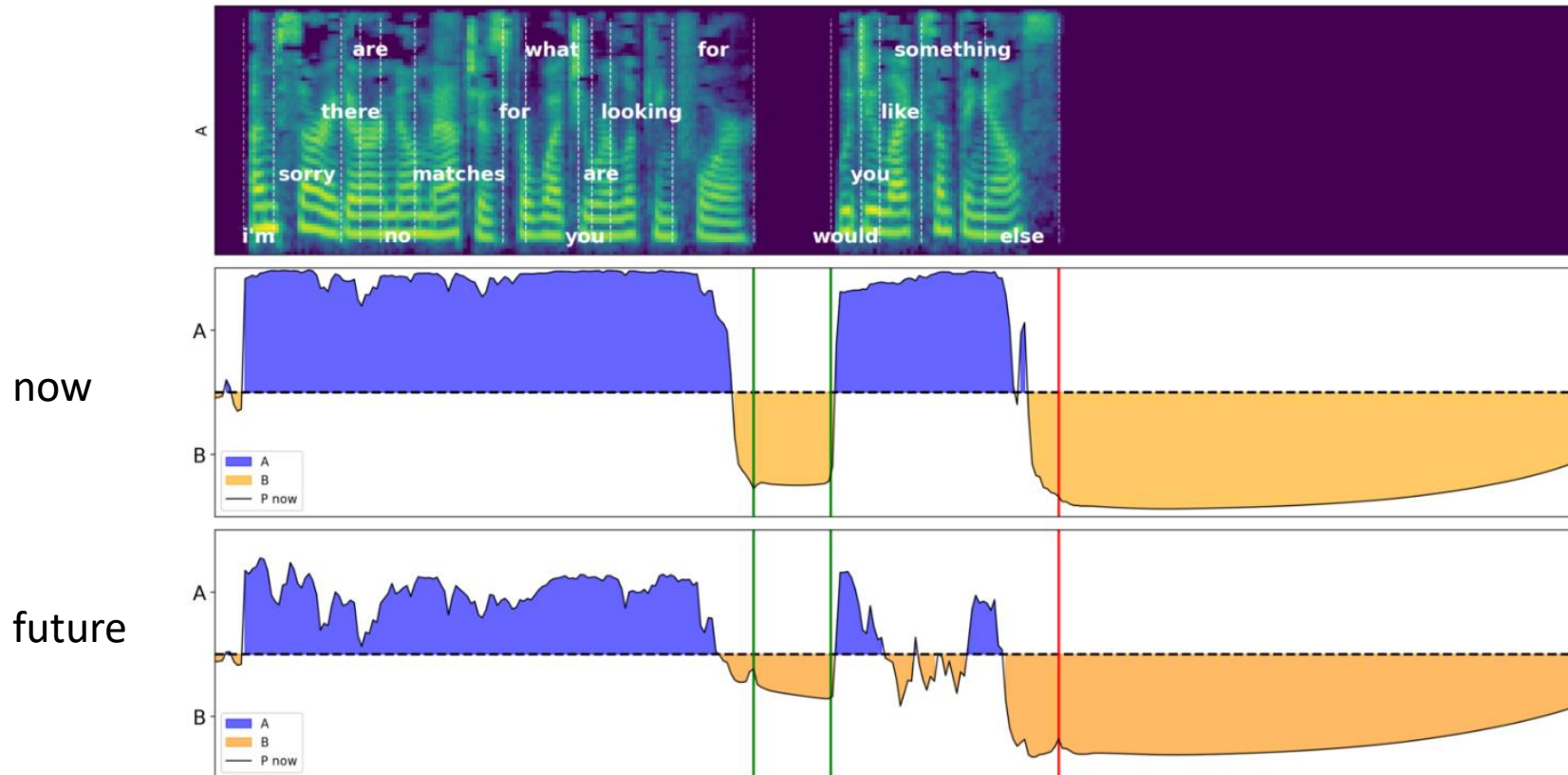
Could you-

System

Yes, I have ABBA gold

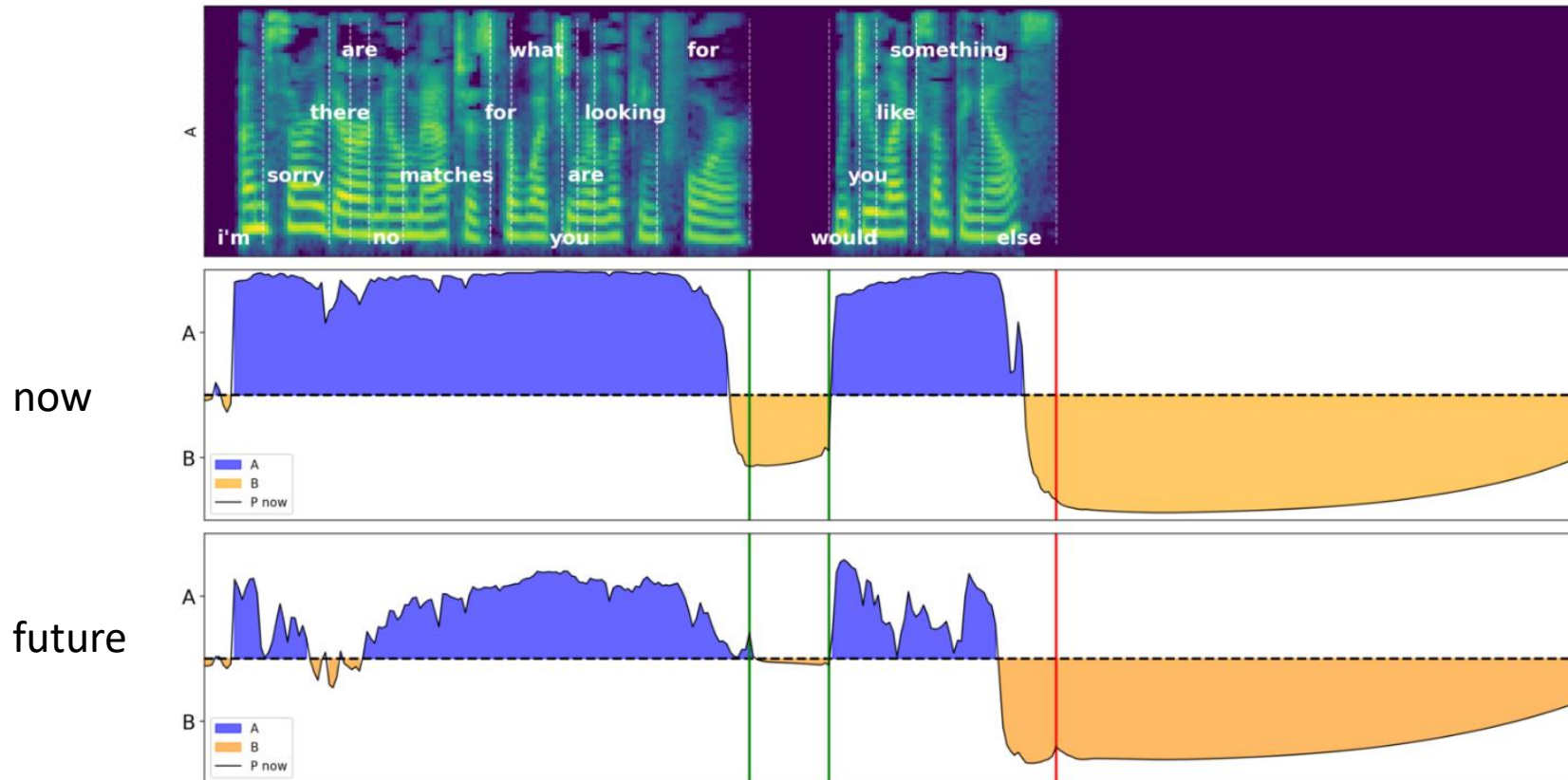
Do you -

Towards a turn-taking aware TTS



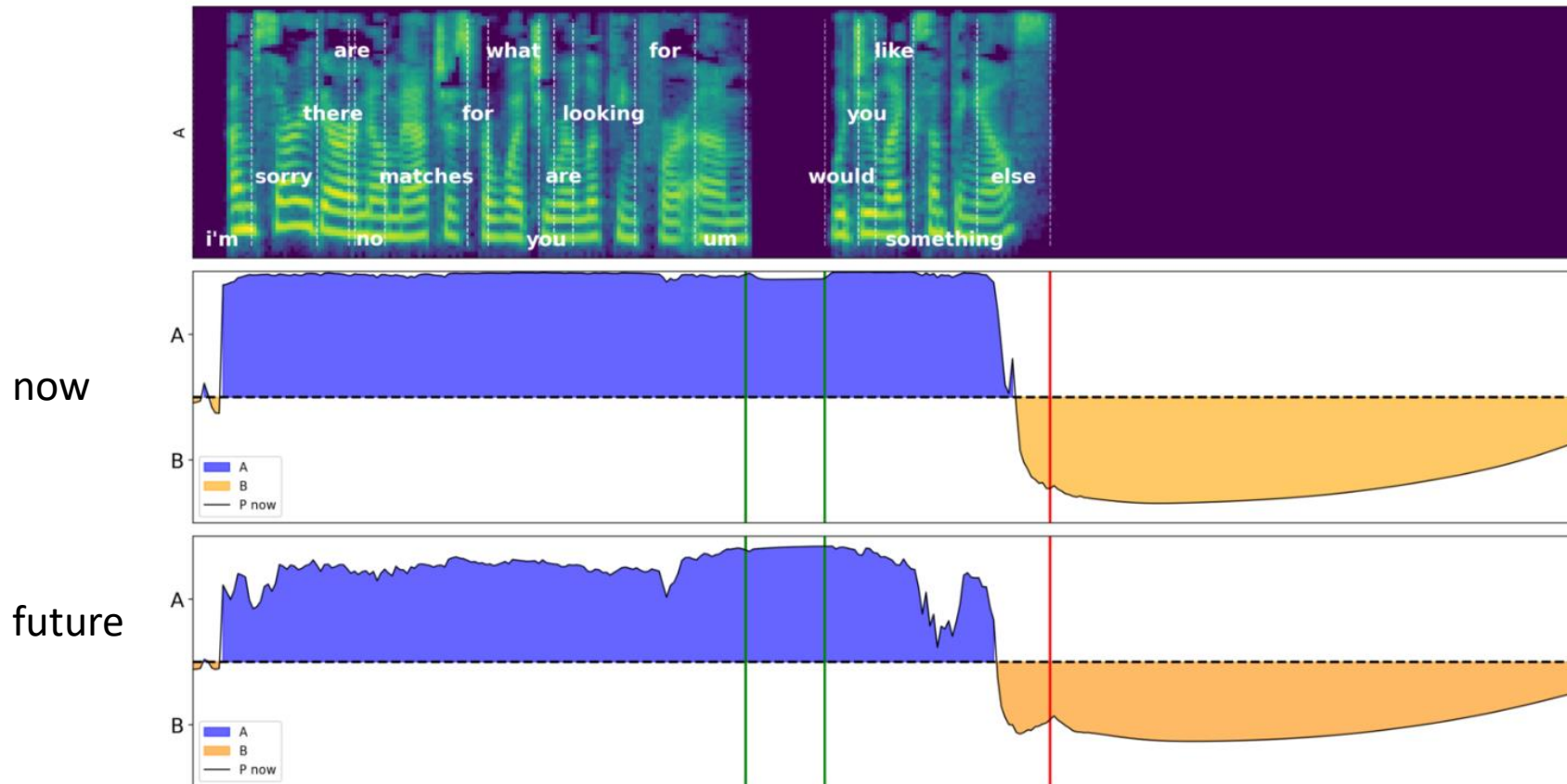
Towards a turn-taking aware TTS

Using a comma



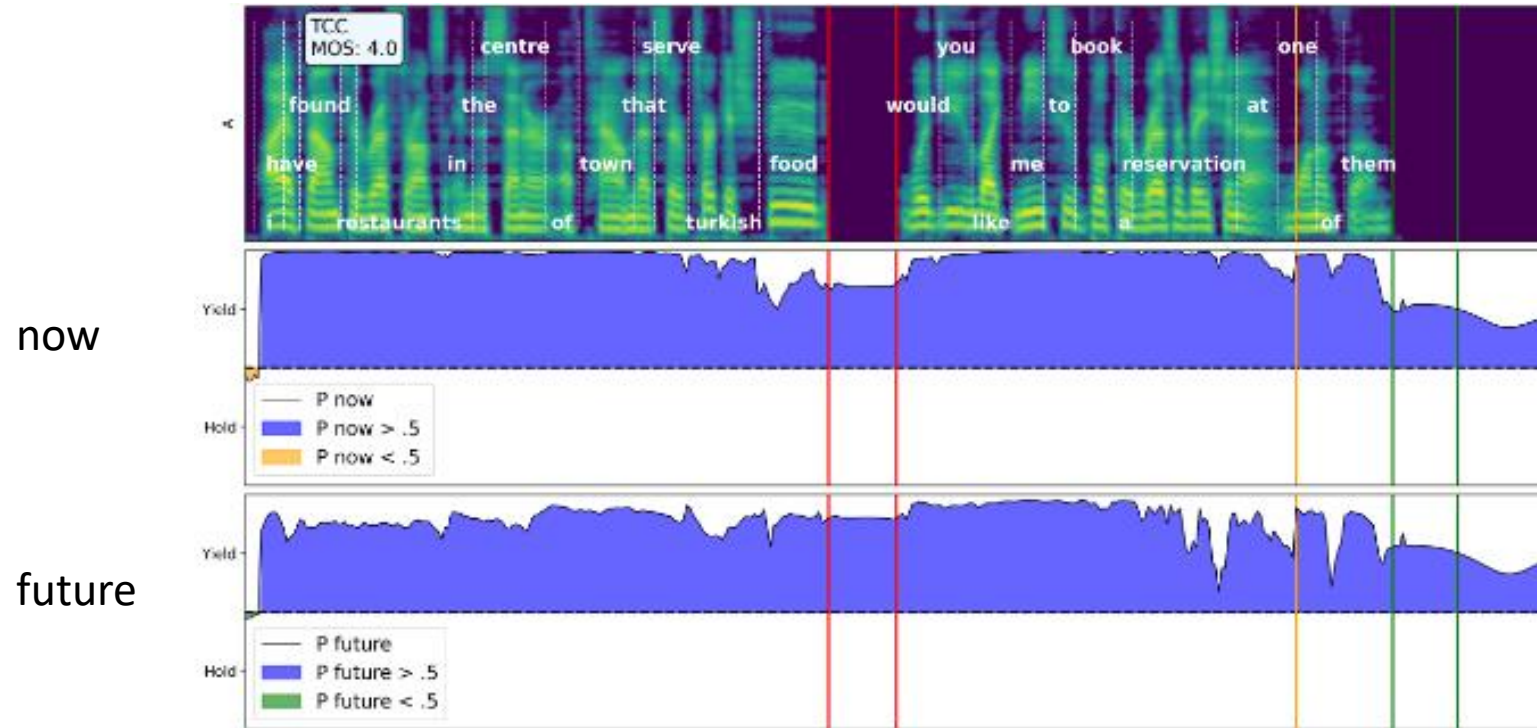
Towards a turn-taking aware TTS

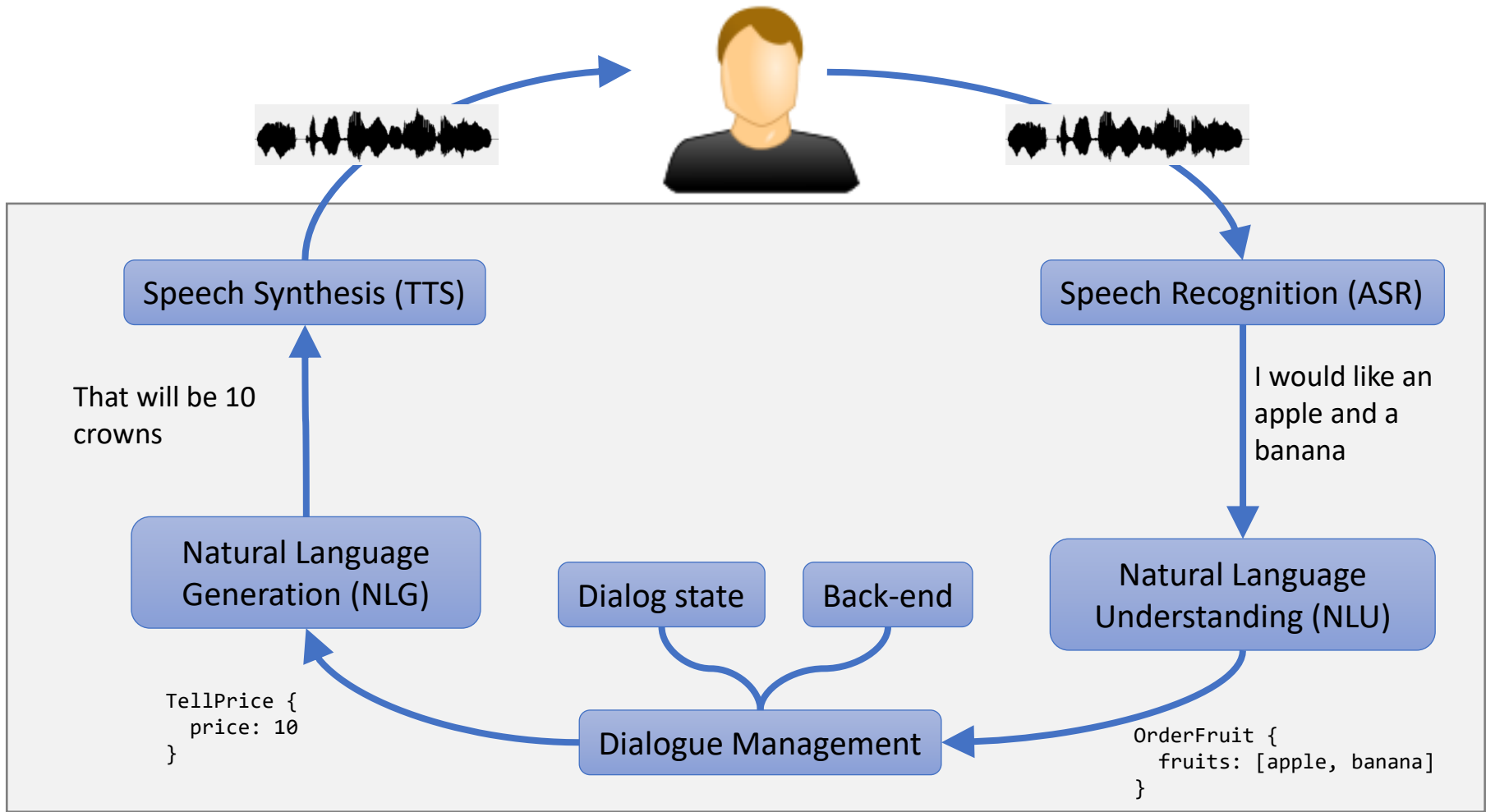
Inserting a filler

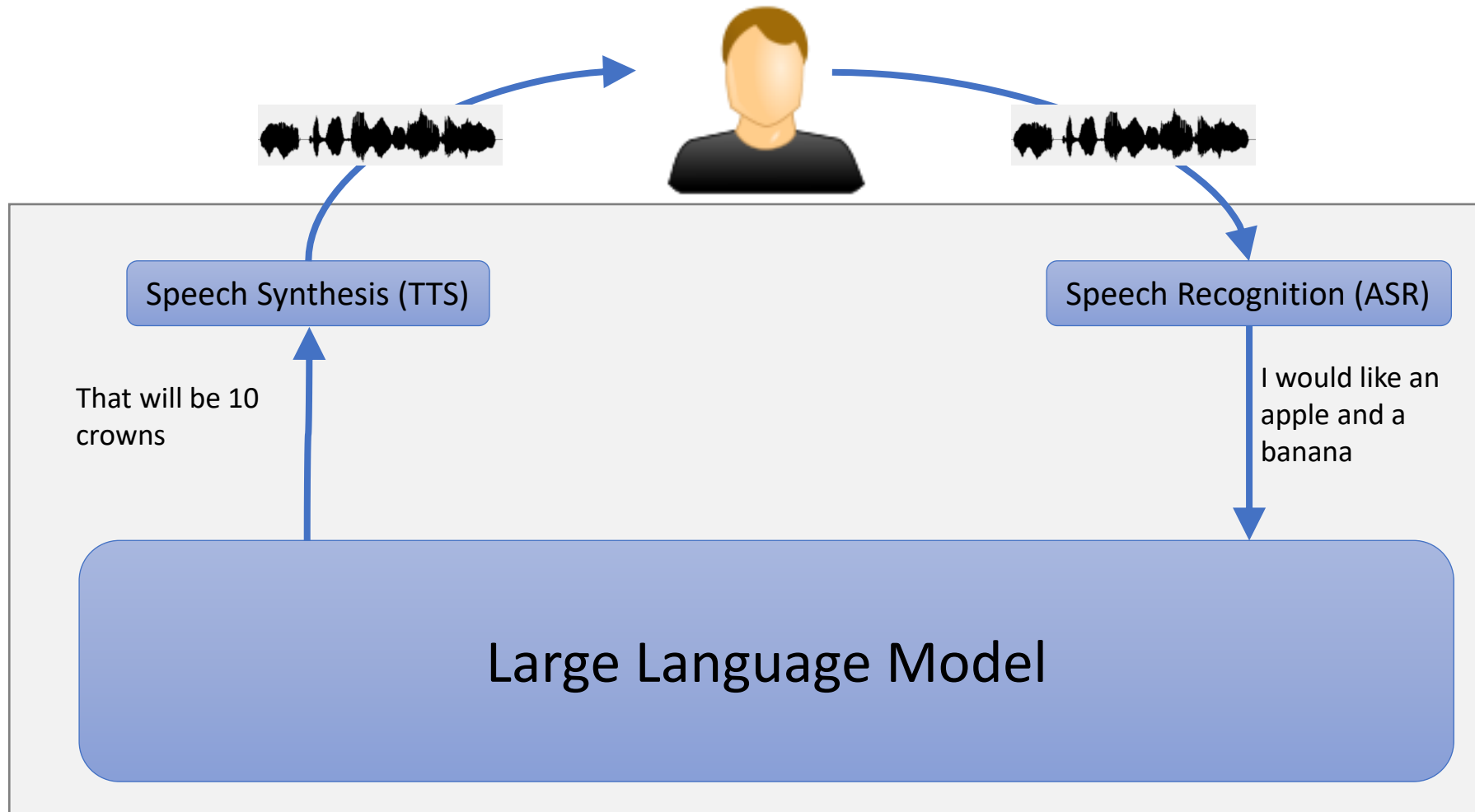


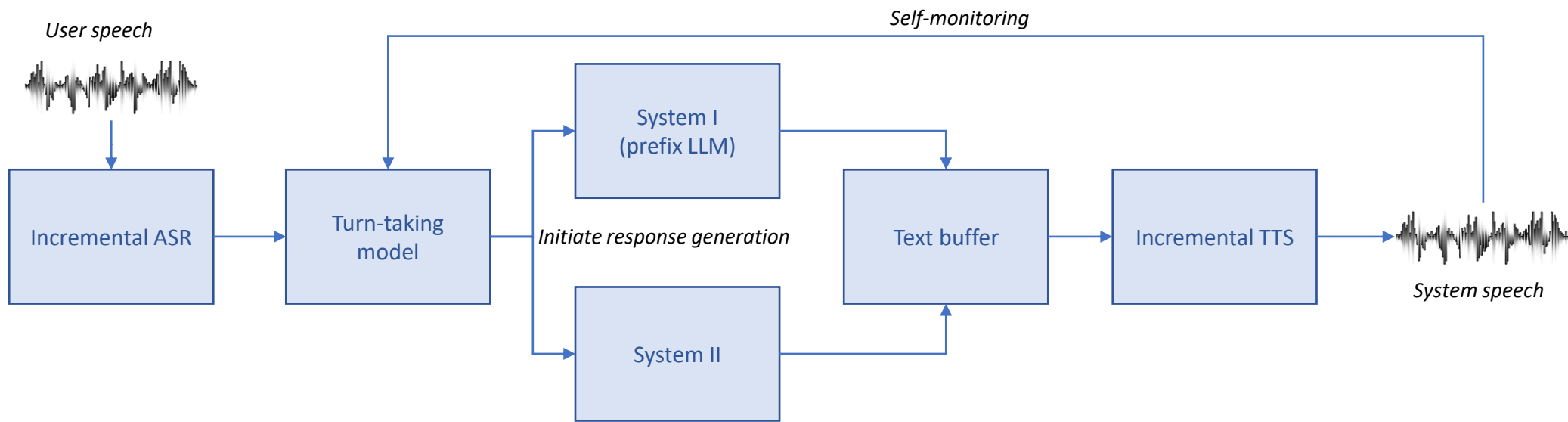
Towards a turn-taking aware TTS

A synthesizer that never yields...









Problems with today's systems

- System are not able to understand the user's turn-taking cues
 - Turn-yielding vs Turn-holding pauses ("endpointing")
 - Back-channel inviting cues
- Systems are purely reactive
 - Do not start planning responses in time
- Systems cannot start to speak before knowing what to say
- Systems cannot distinguish user interruptions from backchannels
- Systems are not aware of their own speech
 - Might accidentally yield or hold the turn in the wrong places

Current/Future work

- Implement VAP in Furhat!
 - How much can you compress the model?
- Comparing languages, multi-lingual models
- Multi-party, Multi-modal
- How can we combine audio and text?
- VAP-tuned TTS
- How can the models be used as a tool to gain insights into human-human dialogue?
 - Cues, Interaction styles, Diagnosis?





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Turn-taking in Conversational Systems and Human-Robot Interaction: A Review



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ABSTRACT

The taking of turns is a fundamental aspect of dialogue. Since it is difficult to speak and listen at the same time, the participants need to coordinate who is currently speaking and when the next person can start to speak. Humans are very good at this coordination, and typically achieve fluent turn-taking with very small gaps and little overlap. Conversational systems (including voice assistants and social robots), on the other hand, typically have problems with frequent interruptions and long response delays, which has called for a substantial body of research on how to improve turn-taking in conversational systems. In this review article, we provide an overview of this research and give directions for future research. First, we provide a theoretical background of the linguistic research tradition on turn-taking and some of the fundamental concepts in theories of turn-taking. We also provide an extensive

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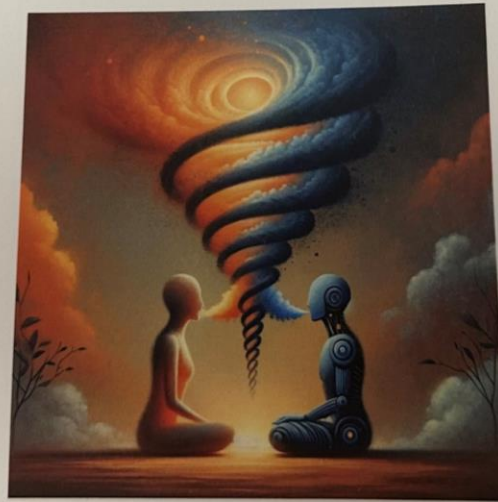


Doctoral Thesis in Speech Communication

Predictive Modeling of Turn-Taking in Spoken Dialogue

Computational Approaches for the Analysis of Turn-Taking in Humans and Spoken Dialogue Systems

ERIK EKSTEDT



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Thank you!

